



JP7 - Motor current output

	Open Collector
	0V / +5V

JP1 - CAN terminator resistor

	CU + Handwheel + K7s
	CU + Handwheel or CU + K7s

JP2,JP3 - Handwheel type select

	CAN
	RS485

JP6 - Handwheel E-STOP type select

	E-STOP 1 only (for old handwheels < 2018)
	E-STOP 1 + E-STOP 2 (for new handwheels > 2018)